Validation Report

New Mexico, SPS-1 Task Order 16, CLIN 2 August 20 to 21, 2008

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1 Executive Summary

A visit was made to the New Mexico 0100 on August 20 to 21, 2008 for the purposes of conducting a validation of the WIM system located on Interstate 25 0.7 mi north of the Rincon interchange. The SPS-1 is located in the righthand, northbound lane of a four-lane divided facility. The posted speed limit at this location is 75 mph. The LTPP lane is the only lane that is instrumented at this site. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This is the first validation visit to this location. The site was installed on April 1 to 30, 2008 by International Road Dynamics Inc. The site was calibrated as a part of the installation process on May 15, 2008. This site has been relocated approximately .5 mile from the previous installation for the SPS-1.

This site demonstrates the ability to produce research quality loading data under the observed conditions. The classification data is also of research quality for Traffic Monitoring Guide Classes based on validation results. However, data from the post-visit download; indicates an unacceptable percentage of unclassified and unknown vehicles.

The site is instrumented with quartz piezo sensors and iSINC electronics. It is installed in asphalt concrete.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 76,670 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 66,920 lbs., the "partial" truck.

The validation speeds ranged from 60 to 75 miles per hour. The pavement temperatures ranged from 81 to 140 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was also achieved.

Table 1-1 – Post-Validation Results – 350100 – 21-Aug-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$0.8 \pm 5.5\%$	Pass
Tandem axles	±15 percent	$1.1 \pm 7.1\%$	Pass
GVW	±10 percent	$1.0 \pm 4.9\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: sfm Checked: bko

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area.

No profile data has been collected at this site since its installation. It is not known when a visit is scheduled to collect it. When profile data becomes available WIMIndex values will be computed and an amended report submitted.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 - Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: sfm Checked: bko

This site needs five years of data to meet the goal of five years of research quality data.

2 Corrective Actions Recommended

Between the installer's calibration of the site and this validation, grinding of the quartz sensors was required to keep them flush with the pavement. The pavement sensor interface should be monitored on maintenance visits.

The post-validation download of records for August 28, 2008 had nearly 5 percent unknown and unclassified vehicles. This clearly exceeds the 2 percent threshold for research quality classification data. The unclassified vehicles should be investigated and the necessary algorithm modifications considered.

3 Post Calibration Analysis

This final analysis is based on test runs conducted August 21, 2008 from mid-morning to mid-afternoon at test site 350100 on Interstate 25. This SPS-1 site is at milepost 36.1 on the northbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 76,670 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 66,920 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 60 to 75 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 81 to 140 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was also achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

Table 3-1 shows that the site is producing research quality loading data.

Table 3-1 - Post-Validation Results – 350100 – 21-Aug-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.8 \pm 5.5\%$	Pass
Tandem axles	±15 percent	$1.1 \pm 7.1\%$	Pass
GVW	±10 percent	$1.0 \pm 4.9\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: sfm Checked: bko

The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and three temperature groups. The distribution of runs by speed

and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was achieved for this set of validation runs.

The three speed groups were divided as follows: Low speed -60 to 64 mph, Medium speed -65 to 71 mph and High speed -72 + mph. The three temperature groups were created by splitting the runs between those at 81 to 100 degrees Fahrenheit for Low temperature, 101 to 125 degrees Fahrenheit for Medium temperature and 126 to 140 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

Figure 3-1 - Post-Validation Speed-Temperature Distribution – 350100 - 21-Aug-2008

Temperature (F)

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. Overestimation of GVW was observed at low speed. Points are scattered in a similar pattern at all speeds. The calibration factor adjustments apparently did not create a similar degree of adjustment for all speed bins.



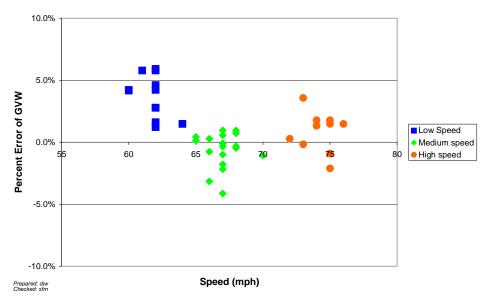


Figure 3-2 - Post-Validation GVW Percent Error vs. Speed - 350100 - 21-Aug-2008

Figure 3-3 shows the relationship between temperature and GVW percentage error. The GVW percent error has a tendency to increase slightly at high temperatures. The scatter is consistent across the temperature bins. The "outlier" for underestimation at medium temperature is a valid data point.

GVW Errors by Temperature

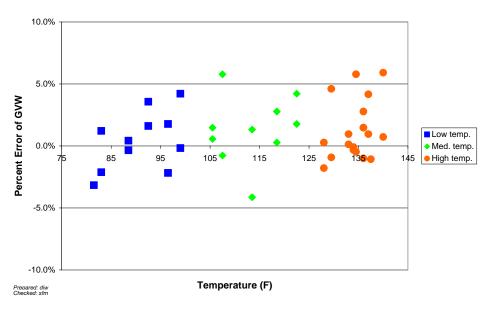


Figure 3-3 - Post-Validation GVW Percent Error vs. Temperature – 350100 - 21-Aug-2008

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Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. The error in spacing is not influenced by speed.

Drive Tandem Spacing vs. WIM Speed

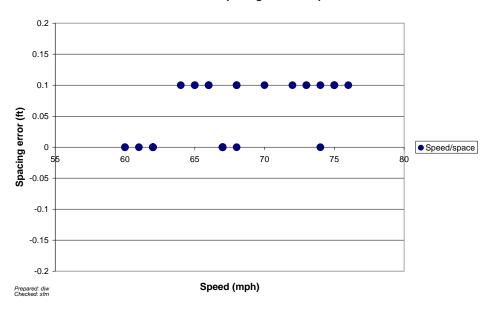


Figure 3-4 - Post-Validation Spacing vs. Speed - 350100 - 21-Aug-2008

3.1 Temperature-based Analysis

The three temperature groups were created by splitting the runs between those at 81 to 100 degrees Fahrenheit for Low temperature, 101 to 125 degrees Fahrenheit for Medium temperature and 126 to 140 degrees Fahrenheit for High temperature.

Table 3-2 - Post-Validation Results by Temperature Bin – 350100 – 21-Aug-2008

Element	95%	Low	Medium	High
	Limit	Temperature	Temperature	Temperature
		81 to 100 °F	101 to 125 °F	126 to 140 °F
Steering axles	<u>+</u> 20 %	$1.6 \pm 6.3\%$	$1.3 \pm 6.3\%$	$0.1 \pm 5.4\%$
Tandem axles	<u>+</u> 15 %	$0.4 \pm 8.0\%$	$1.4 \pm 8.0\%$	$1.4 \pm 6.7\%$
GVW	<u>+</u> 10 %	$0.4 \pm 5.2\%$	$1.3 \pm 6.1\%$	$1.2 \pm 4.9\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.1 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: sfm Checked: bko

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph. The trucks have similar patterns with temperature. The scatter across temperatures appears to be less with the partial truck (diamonds) than with the golden truck (squares).

GVW Errors vs. Temperature by Truck

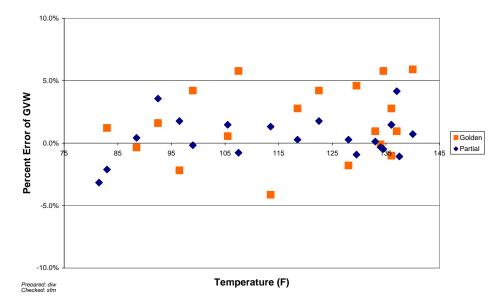


Figure 3-5 - Post-Validation GVW Percent Error vs. Temperature by Truck $-\,350100-21\text{-Aug-}2008$

Figure 3-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

Temperature does not appear to influence scatter of steering axle error. There appears to be a slight decrease in error with increasing temperature.

Steering Axle Errors vs. Temperature

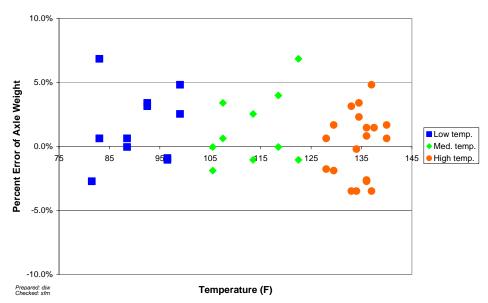


Figure 3-6 - Post-Validation Steering Axle Error vs. Temperature by Group -350100-21-Aug-2008

3.2 Speed-based Analysis

The three speed groups were created using 60 to 64 mph for Low speed, 65 to 71 mph for Medium speed and 72+ mph for High speed.

Table 3-3 - Post-Validation Results by Speed Bin – 350100 – 21-Aug-2008

Element	95% Limit	Low Speed	Medium Speed	High Speed
		60 to 64 mph	65 to 71 mph	72+ mph
Steering axles	<u>+</u> 20 %	$3.1 \pm 4.9\%$	$-0.2 \pm 5.0\%$	$0.0 \pm 5.4\%$
Tandem axles	<u>+</u> 15 %	$3.7 \pm 6.6\%$	$-0.7 \pm 6.1\%$	$1.3 \pm 6.5\%$
GVW	<u>+</u> 10 %	$3.7 \pm 3.8\%$	$-0.6 \pm 3.0\%$	$0.8 \pm 3.6\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	0.1 ± 0.1 ft	$0.1 \pm 0.1 \text{ ft}$
			Prepared:	sfm Checked: bko

Figure 3-7 shows the results for GVW errors by truck with speed. The golden truck (squares) did not run at high speed due to an engine governor limiting it to 68 mph. As the 85 percentile speed at this site using the WIM data is 65 mph, this was not considered detrimental to the validation.

The overestimation of GVW is higher at low speed. This may reflect the characteristics of the golden truck which completed the majority of runs at this speed. The amount of scatter for both trucks is similar at all speeds.

GVW Errors vs. Speed

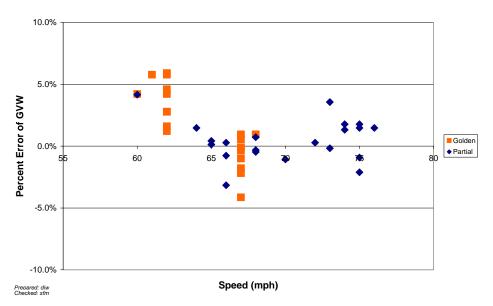


Figure 3-7 - Post-Validation GVW Percent Error vs. Speed by Truck-350100-21-Aug-2008

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

Steering axle error is overestimated at low speed. There is a downward trend in steering axle errors with increasing speed.

Steering Axle Errors vs. Speed

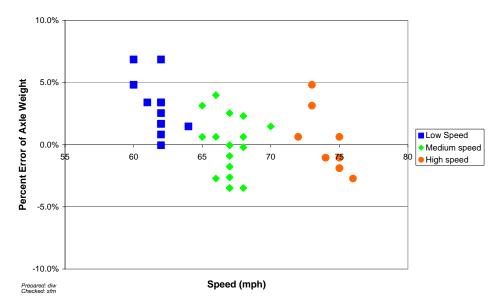


Figure 3-8 - Post-Validation Steering Axle Percent Error vs. Speed by Group -350100-21-Aug-2008

3.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles. Classification 14 is included for unknown vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles. **This is inconsistent with the data in the post-validation download.**

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The overall misclassification rate is 2.0 percent.

Table 3-4 - Truck Misclassification Percentages for 350100 – 21-Aug-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	0	5	11	6	0
7	N/A				
8	10	9	0	10	N/A
11	0	12	0	13	N/A

Prepared: sfm

Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 - Truck Classification Mean Differences for 350100 - 21-Aug-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	0	5	- 11	6	0
7	N/A				
8	11	9	0	10	N/A
11	0	12	0	13	N/A

Prepared: sfm Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. The difference may be associated with the measurement technique.

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 - Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: sfm Checked: bko

4 Pavement Discussion

The pavement condition did not appear to influence truck movement across the sensors.

4.1 Profile Analysis

Profile data collected since the site installation does not exist. It is not known when a visit is scheduled to collect it. An amended report will be submitted when the data is available.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement no distresses that would influence truck movement across the WIM scales were noted.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires and any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes quartz piezo sensors and iSINC electronics. The sensors are installed in an asphalt concrete pavement.

Between the installation of the site and the beginning of the validation the pavement sank around the WIM sensors. This produced a bump in the pavement that required grinding the WIM sensors to make them once again flush with the pavement surface.

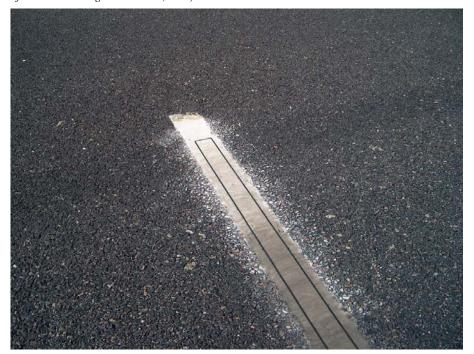


Photo 5-1 - Results of Grinding Leading WIM Sensor at Lane's Edge $\,$ - 350100 - 20- Aug-2008

The grinding was done along the entire width of the lane for both sensors. Photo 5-1 shows the aftermath of grinding the leading WIM sensor all the way to the edge of the lane. Photo 5-2 shows the results of the same activity for the trailing sensor where the dust from grinding has dispersed from the wheelpath.



Photo 5-2 – Results of Grinding of Trailing Sensor - Full Lane Width - 350100 - 20-Aug-2008

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. All sensors and system components were found to be within operating parameters.

5.2 Calibration Process

The equipment required one-iteration of the calibration process between the initial 40 runs and the final 40 runs to remove the observed bias.

The operating system weight compensation parameters that were in place prior to the Pre-Validation are in Table 5-1. The sensors are labeled simply 1 and 2 rather than right and left since this installation uses sensors across the full width of the roadway.

Table 5-1 - Initial System Parameters - 350100 - 20-Aug-2008

Speed Bin	Sensor 1	Sensor 2
88 kph	3315	2962
96 kph	3315	2962
105 kph	3332	2975
112 kph	3332	2975
120 kph	3332	2975

Prepared: sfm

Checked: bko

5.2.1 Calibration Iteration 1

GVW was overestimated by approximately five percent at all speeds. The compensation factors were adjusted as shown in Table 5-2.

Table 5-2 - Calibration 1 - Change in Parameters - 350100 - 21-Aug-2008

Speed Bins	Sensor 1	Change	Sensor 2	Change
88 kph	3315		2962	
96 kph	3315		2962	
105 kph	3158	5.2%	2819	5.2%
112 kph	3146	5.6%	2809	5.6%
120 kph	3163	5.1%	2824	5.1%

Prepared: sfm Checked: bko

Table 5-3 shows the results of applying the factor adjustments after the initial 12 validation runs. The loading data is essentially unbiased over the range of speeds for a post-calibration verification.

Table 5-3 - Calibration Iteration 1 Results - 350100 - 21-Aug-2008 (08:17 AM)

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.2 \pm 6.2\%$	Pass
Tandem axles	±15 percent	$0.0 \pm 7.9\%$	Pass
GVW	±10 percent	$-0.1 \pm 5.2\%$	Pass
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: sfm Checked: bko

GVW Errors by Speed

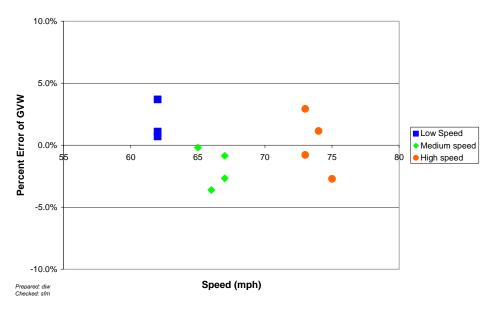


Figure 5-1 - Calibration Iteration 1 GVW Percent Error vs. Speed Group – 350100 – 21-Aug-2008 (08:17 AM)

5.3 Summary of Traffic Sheet 16s

Table 5-4 has the information for TRF_CALIBRATION_AVC for Sheet 16s for the current visit. The Sheet 16s available reflect only this contractor's validation visits and the current sensor installation.

Table 5-4 - Classification Validation History – 350100 – 21-Aug-2008

Date	Method		Mean Difference			
		Class 9	Class 8	Other 1	Other 2	Unclassified
21-Aug-08	Manual	11	0	-	-	0.0
20-Aug-08	Manual	0	0	0 (class 5)	-	0.0

Prepared: sfm Checked: bko

Table 5-5 has the information for TRF_CALIBRATION_WIM for Sheet 16s submitted for the current visit. The Sheet 16s available are only for this contractor's validation visit and the current sensor installation.

Table 5-5 - Weight Validation History – 350100 – 21-Aug-2008

Date	Method	Mean Error and (SD)			
		GVW	Single Axles	Tandem Axles	
21-Aug-08	Test trucks	1.0 (2.4)	0.8 (2.7)	1.1 (3.6)	
20-Aug-08	Test trucks	5.0 (1.6)	2.1 (2.3)	5.7 (3.1)	

Prepared: sfm

Checked: bko

5.4 Projected Maintenance/Replacement Requirements

The sensors at this site have been ground since the installation calibration to make them flush with the pavement. Evidence of grinding appears in Figure 5-2 and Figure 5-3.



Figure 5-2 - Illustration of Grinding at End of Sensor Array - 350100 - 20-Aug-2008



Figure 5-3 - Illustration of Grinding at Shoulder Edge of Sensor - 350100 - 20-Aug-2008

Vehicles traversing the sensors have removed the grinding residue from the wheel path.

This site is scheduled for semi-annual maintenance under the installation contract. The pavement sensor interface will need to be monitored at future site visits.

6 Pre-Validation Analysis

This Pre-Validation analysis is based on test runs conducted August 20, 2008 from midmorning to mid-afternoon at test site 350100 on Interstate 25. This SPS-1 site is at milepost 36.1 on the northbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 76,430 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 66,790 lbs., the "partial" truck.

For the initial validation each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 58 to 75 miles per hour. The desired speed range was achieved during this validation.

Pavement surface temperatures were recorded during the test runs ranging from about 75 to 138 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was also achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

Table 6-1 shows that the site was producing research quality data at the beginning of the validation. However, the loading statistics indicate that weights were being overestimated. In the case of GVW the overestimation is approximately five percent. On the basis of that bias a calibration iteration was considered necessary.

Table 6-1 - Pre-Validation Results – 350100 – 20-Aug-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$2.1 \pm 4.7\%$	Pass
Tandem axles	±15 percent	$5.7 \pm 6.2\%$	Pass
GVW	±10 percent	$5.0 \pm 3.2\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: sfm Checked: bko

The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and three temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired

distribution of speed and temperature combinations was achieved for this set of validation runs.

The three speed groups were divided into 58 to 64 mph for Low speed, 65 to 71 mph for Medium speed and 72+ mph for High speed. The three temperature groups were created by splitting the runs between those at 75 to 96 degrees Fahrenheit for Low temperature, 97 to 119 degrees Fahrenheit for Medium temperature and 120 to 138 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

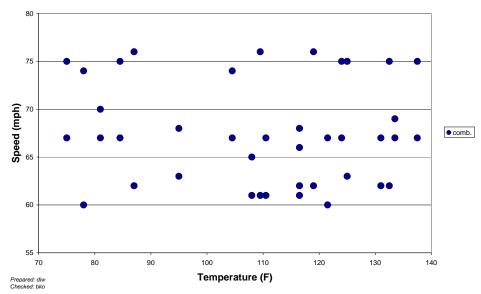


Figure 6-1 - Pre-Validation Speed-Temperature Distribution – 350100 – 20-Aug-2008

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. The overestimation of GVW was observed at all speeds with essentially the same degree of scatter.

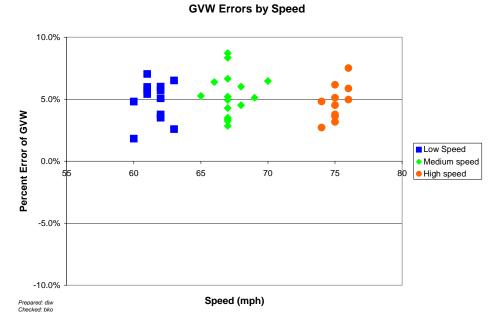


Figure 6-2 - Pre-Validation GVW Percent Error vs. Speed – 350100 – 20-Aug-2008

Figure 6-3 shows the relationship between temperature and GVW percentage error. It shows the overestimation of GVW which appears consistent for all temperatures.

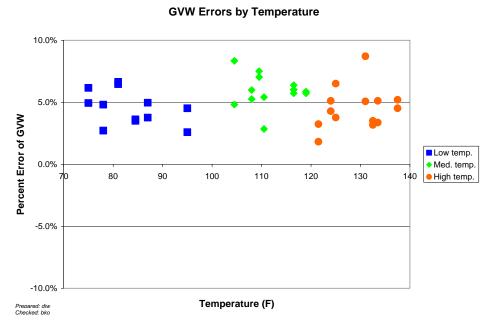


Figure 6-3 - Pre-Validation GVW Percent Error vs. Temperature – 350100 - 20-Aug-2008

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speed. This graph is used as a potential indicator of classification errors due to failure to

correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Speed has no apparent influence on spacing errors.

Drive Tandem Spacing vs. WIM Speed

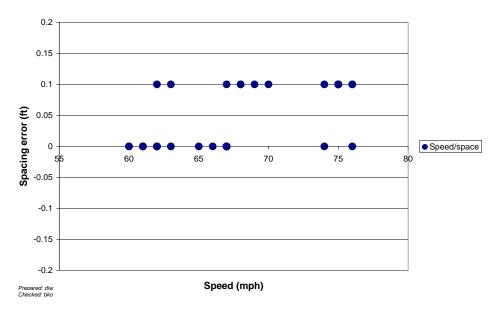


Figure 6-4 - Pre-Validation Spacing vs. Speed - 350100 – 20-Aug-2008

6.1 Temperature-based Analysis

The three temperature groups were created by splitting the runs between those at 75 to 96 degrees Fahrenheit for Low temperature, 97 to 119 degrees Fahrenheit for Medium temperature and 120 to 138 degrees Fahrenheit for High temperature.

Table 6-2 - Pre-Validation Results by Temperature Bin – 350100 – 20-Aug-2008

Element	95% Limit	Low Temperature 75 to 96 °F	Medium Temperature 97 to 119 °F	High Temperature 120 to 138 °F
Steering axles	<u>+</u> 20 %	$2.3 \pm 3.8\%$	$3.0 \pm 5.0\%$	$1.0 \pm 5.3\%$
Tandem axles	<u>+</u> 15 %	$5.1 \pm 5.8\%$	$6.8 \pm 6.0\%$	$5.2 \pm 6.8\%$
GVW	<u>+</u> 10 %	$4.6 \pm 3.0\%$	$5.9 \pm 2.8\%$	$4.5 \pm 3.6\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	0.1 ± 0.1 ft
	-		Prepared: s	sfm Checked: bko

Table 6-2 shows overestimation is higher for all elements at medium temperature.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. There is no apparent temperature trend.

GVW Errors vs. Temperature by Truck

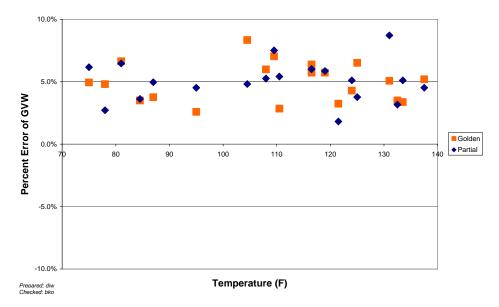


Figure 6-5 - Pre-Validation GVW Percent Error vs. Temperature by Truck-350100-20-Aug-2008

Figure 6-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

Figure 6-6 shows overestimation of steering axle errors at all temperatures. The scatter in the error appears to increase with increasing temperature.

Steering Axle Errors vs. Temperature

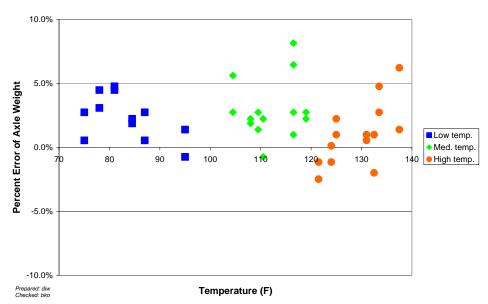


Figure 6-6 - Pre-Validation Steering Axle Error vs. Temperature by Group – 350100 – 20-Aug-2008

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -58 to 64 mph, Medium speed -65 to 71 mph and High speed -72+ mph.

Table 6-3 - Pre-Validation Results by Speed Bin – 350100 – 20-Aug-2008

Element	95%	Low	Medium	High
	Limit	Speed	Speed	Speed
		58 to 64 mph	65 to 71 mph	72+ mph
Steering axles	<u>+</u> 20 %	$2.1 \pm 5.1\%$	$2.5 \pm 5.2\%$	$1.5 \pm 4.6\%$
Tandem axles	<u>+</u> 15 %	$5.5 \pm 6.2\%$	$6.0 \pm 6.7\%$	$5.7 \pm 6.3\%$
GVW	<u>+</u> 10 %	$4.9 \pm 3.4\%$	$5.3 \pm 3.7\%$	$4.7 \pm 3.1\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.1 \pm 0.1 \text{ ft}$

Prepared: sfm Checked: bko

GVW and tandem axles are overestimated by approximately five percent at all speeds. The variability is consistent at all speeds. Steering axle error is overestimated as well but not as much.

Figure 6-7 shows GVW percent error is consistently over estimated for both trucks at all speeds. The scatter is approximately the same for both trucks.

The runs at high speed are limited to the "Partial" truck (diamonds) since the Golden truck (squares) had a speed governor on the engine.



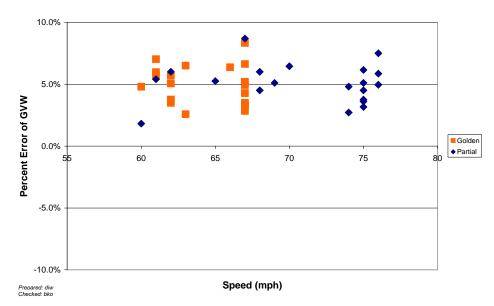


Figure 6-7 - Pre-Validation GVW Percent Error vs. Speed Group - 350100 –20-Aug-2008

Figure 6-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Steering axle error is consistent at all speeds.

Steering Axle Errors vs. Speed

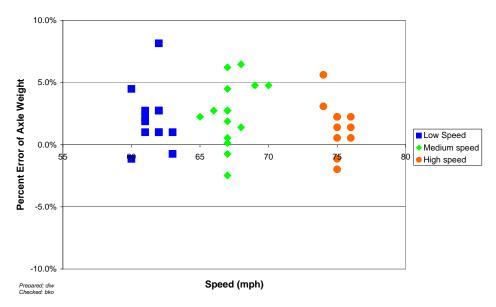


Figure 6-8 - Pre-Validation Steering Axle Percent Error vs. Speed Group - 350100 - 20-Aug-2008

6.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles. Classification 14 is included for unknown vehicles.

A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles. **This is inconsistent with the data in the post-validation download.**

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is zero percent.

Table 6-4 - Truck Misclassification Percentages for 350100 - 20-Aug-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	0	13	N/A

Prepared: sfm Checked: bkd

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations

with at least one Class 9 and only six of them a re matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-5 - Truck Classification Mean Differences for 350100 - 20-Aug-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	0	13	N/A

Prepared: sfm Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over- or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. The measurement method is thought to be the underlying cause.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 - Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: sfm Checked: bko

7 Data Availability and Quality

As of August 20, 2008 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site is shown in Table 7-1. The value for months is a measure of the seasonal variation in the data. The indicator of coverage indicates whether day of week variation has been accounted for on an annual basis. This site is a new installation. In the absence of validation information for previous sensor installations no earlier data is included for this site.

Table 7-1 - Amount of Traffic Data Available 350100 – 20-Aug-2008

Year	Classification Days	Months	Coverage	Weight Days	Months	Coverage
2008	41	2	Full week	41	2	Full week

Prepared: sfm Checked: bko

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 9s and Class 5s constitute more than 10 percent of the truck population. Based on the data collected following this validation the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the Regional Support Contractor on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-2 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-2 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.

page 28

- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- o For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.
- o For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-2 - GVW Characteristics of Major sub-groups of Trucks – 350100 – 21-Aug-2008

Characteristic	Class 9	Class 5
Percentage Overweights	0.0%	0.0%
Percentage Underweights	0.5%	0.0%
Unloaded Peak	36,000 lbs	
Loaded Peak	72,000 lbs	
Peak		16,000 lbs

Prepared: sfm Checked

The expected percentage of unclassified and unknown vehicles is 4.7 percent. This is based on the percentage of unclassified and unknown vehicles in the Post-Validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-4. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the Post-Validation period.

Class 9 GVW Distribution

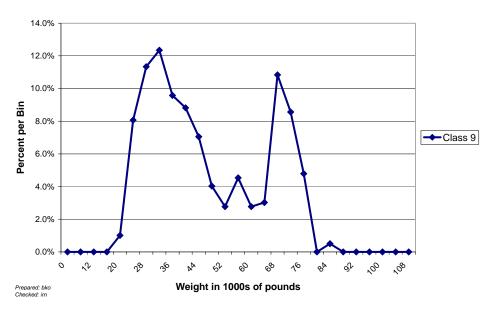


Figure 7-1 - Expected GVW Distribution Class 9 - 350100 - 21-Aug-2008



Figure 7-2 - Expected GVW Distribution Class 5 - 350100 - 21-Aug-2008

Vehicle Distribution Trucks (4-15)

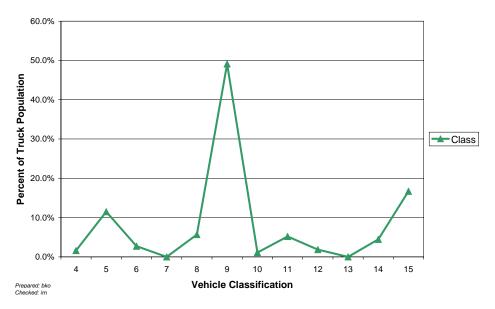
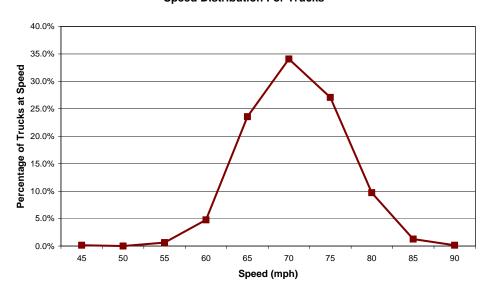


Figure 7-3 - Expected Vehicle Distribution - 350100 - 21-Aug-2008



Speed Percentage

Speed Distribution For Trucks

Figure 7-4 - Expected Speed Distribution – 350100 – 21-Aug-2008

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

Sheet 19 - Truck 1 - 3S2 loaded air suspension (3 pages) Sheet 19 - Truck 2 - 3S2 partially loaded air suspension (3 pages)

```
Sheet 20 – Classification verification – pre-validation (2 pages)
Sheet 20 – Classification verification – post-validation (2 pages)
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Sheet 21 – Pre-Validation (3 pages)

Sheet 21 – Calibration Iteration 1 – (1 page)

Sheet 21 – Post-Validation (2 pages)

Calibration Iteration 1 Worksheets – (1 page)

Test Truck Photographs (6 pages)

LTPP Mod 3 Classification Scheme (1 page)

Final System Parameters (1 page)

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following this page. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the Pre-Validation and Post-Validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: New Mexico

SHRP ID: 0100

1.	General Information	1
2.	Contact Information	1
3.	Agenda	1
	Site Location/ Directions	
5.	Truck Route Information	3
	Sheet 17 – New Mexico (350100)	

Figures

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Figure 5-1 – Scale Location for 350100 in New Mexico	
Figure 5-2 – Truck Route for 350100 in New Mexico	
Figure 6-1 – Site Map for 350100 in New Mexico	
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Photo 2 - 350100_Downstream_08_20_08.jpg	8
Photo 3 - 350100_Power_Meter_08_20_08.jpg	
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Photo 5 - 350100_Cell_Modem_08_20_08.jpg	
Photo 6 - 350100_Cabinet_Exterior_08_20_08.jpg	
Photo 7 - 350100_Cabinet_Interior_Front_08_20_08.jpg	
Photo 8 - 350100_Cabinet_Interior_Back_08_20_08.jpg	
Photo 9 - 350100_Leading_WIM_Sensor_08_20_08.jpg	
Photo 10 - 350100_Trailing_WIM_Sensor_08_20_08.jpg	
Photo 11 - 350100_Leading_Loop_08_20_08.jpg	
Photo 12 - 350100_Trailing_Loop_08_20_08.jpg	

Validation – NM 0100 MACTEC Ref. 6420060018 2.81
Assessment, Calibration and Performance Evaluation 9/10/2008
of LTPP SPS Weigh-in-Motion (WIM) Sites Page 1 of 13

1. General Information

SITE ID: 350100

LOCATION: Interstate 25 North at M.P. 36.1

VISIT DATE: August 20, 2008

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: Bruce Bender, 505-827-5508, <u>bruced.bender@state.nm.us</u>
Robert Meyers, 505-827-5466, <u>robert.meyers@state.nm.us</u>
Parveez Anwar, 505-827-5656, <u>parveez.anwar@state.nm.us</u>

FHWA COTR: Debbie Walker, 202-493-3068, <u>deborah.walker@fhwa.dot.gov</u>

FHWA Division Office Liaison: Steven Von Stein, 505-820-2028, steven.von.stein@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: No briefing requested for this visit

ON SITE PERIOD: August 20 - 21, 2008, beginning at 9:00 a.m.

TRUCK ROUTE CHECK: See Truck Route

4. Site Location/ Directions

NEAREST AIRPORT: El Paso International Airport, El Paso, Texas

DIRECTIONS TO THE SITE: 0.7 mi. north of Rincon Interchange

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: Interstate 25 North at M.P. 36.1 (Latitude: 32.6777⁰ and

Longitude: -107.0654⁰)

WIM SITE LOCATION MAP: See Figure 4.1



Figure 4-1 – Site Location for 350100 in New Mexico

5. Truck Route Information

ROUTE RESTRICTIONS: None

SCALE LOCATION: *TA Las Cruces, I-10, exit 139, 505-527-7400, Latitude: 32.30044*⁰, *Longitude: -106.81306*⁰.

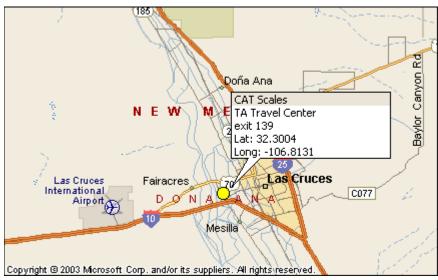


Figure 5-1 – Scale Location for 350100 in New Mexico

TRUCK ROUTE:

- Northbound to Exit 41 Interchange (5.0 miles). West 0.2 miles, turnaround on right out of turnaround, East 200 feet to I-25 ramp.
- Southbound to Exit 32 Interchange (3.5 miles).



Figure 5-2 – Truck Route for 350100 in New Mexico

6. Sheet 17 – New Mexico (350100)

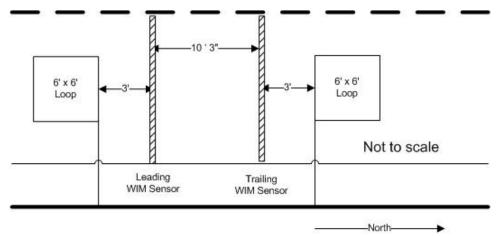
1.* ROUTE	_I-25	MILEPOST	_36.1_	LTPP DIRE	ECTION - N S E W
Nearest	SPS section d	ownstream of t	he site	350101	$\begin{array}{c} \text{ag vertical } Y / \underline{N} \\ \underline{-850} & \text{ft} \end{array}$
3.* LANE CON Lanes in		N on <u>2</u>		Lane width	_ <u>12</u> _ ft
Median	1 – pair 2 – phy 3 – gra 4 – non	sical barrier ss		Shoulder -	1 – curb and gutter 2 – paved AC 3 – paved PCC 4 – unpaved 5 – none
Shoulde	er width <u>14</u>	_ ft			
4.* PAVEMEN	NT TYPE	<u> Asphalt</u>			
	<u>)8</u> Filename _	35_0100_U ₁	ostream	08 20 2008	.jpg
Date _ <u>8/20/200</u>					008.jpg
	EMENT AND/O	_	G	// //	
distance Intersec distance	etion/driveway eetion/driveway ee	within 300 m ı	lownstr	eam of sensor	cation Y / <u>N</u> location Y / <u>N</u>
9. DRAINAG	E (Bending plo	nte and load ce	ll syster	ms only)	1 – Open to ground 2 – Pipe to culvert 3 – None
	_	· · ush fines from		ystem Y / N	

10. * CABINET LOCATION Same side of road as LTPP lane \underline{Y} / N Median $\underline{Y} / \underline{N}$ Behind barrier $\underline{Y} / \underline{N}$ Distance from edge of traveled lane __50__ ft Distance from system __56__ ft TYPE _____336S CABINET ACCESS controlled by LTPP / STATE / JOINT? Contact - name and phone number ____ Robert Meyers (505) 827-5466 ___ Alternate - name and phone number _____ 11. * POWER Distance to cabinet from drop ____ _12_ ___ ftOverhead / underground / solar / AC in cabinet? Service provider ____N/A_____ Phone number ____N/A_____ 12. * TELEPHONE Distance to cabinet from drop ____ N/A __ ft Overhead / under ground / cell? Service provider _earthlink_ Phone _newmexicosps1wim.earthlink.com/2100_ 13.* SYSTEM (software & version no.)- ___iSINC_ Computer connection – RS232 / Parallel port / USB / Other 14. * TEST TRUCK TURNAROUND time _____20__ minutes DISTANCE __15__ mi. 15. PHOTOS **FILENAME** 350100 Power Meter 08 20 2008.jpg Power source 350100_ Service_Mast_08_20_08.jpg_____ 350100_Cell_Modem_08_20_2008.jpg _____ Phone source 350100 Cabinet Exterior 08 20 2008.jpg Cabinet exterior Cabinet interior 350100_Cabinet_Interior_Front_08_20_2008.jpg 350100 Cabinet Interior Back 08 20 2008.jpg 350100_Leading_WIM_Sensor_08_20_2008.jpg _____ Weight sensors __350100_Trailing_WIM_Sensor _08_20_2008.jpg_____ Classification sensors <u>none</u> 350100_Leading_Loop_08_20_2008.jpg_____ Other sensors 350100 Trailing Loop 08 20 2008.jpg Description ___Loops_ Downstream direction at sensors on LTPP lane 35 0100_Downstream 08_20_2008.jpg Upstream direction at sensors on LTPP lane 35_0100_Upstream_08_20_2008.jpg____

Validation – NM 0100 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites MACTEC Ref. 6420060018 2.81 9/10/2008 Page 6 of 13

CC	N	/I N	N I' I	
	,,,	/	V	

GPS Coordinates: Latitude: 32 ⁰ 40.642' and Longitude: 107 ⁰ 4.030'
<u> </u>
Closest Amenities 32 miles south of site in Las Cruces
Various Hotels, Restaurants, Gas Stations, Lowe's, Wal-Mart
No SPS Test Section Upstream
COMPLETED BYDean J. Wolf
PHONE 301-210-5105 DATE COMPLETED 8/20/2008



6-1 Sketch of Equipment Layout - 350100

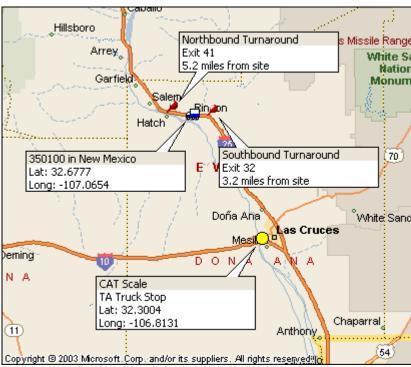


Figure 6-2 – Site Map for 350100 in New Mexico

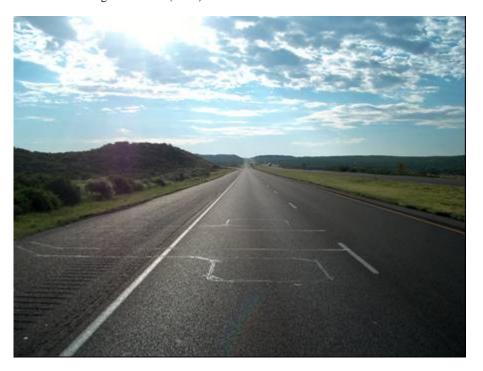


Photo 1 - 350100_Upstream_08_20_08.jpg

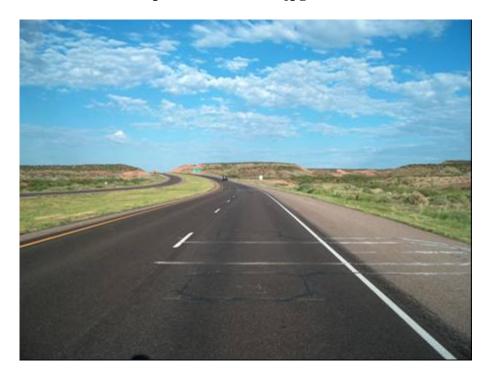


Photo 2 - 350100_Downstream_08_20_08.jpg



Photo 3 - 350100_Power_Meter_08_20_08.jpg



Photo 4 - 350100_Service_Mast_08_20_08.jpg



Photo 5 - 350100_Cell_Modem_08_20_08.jpg



Photo 6 - 350100_Cabinet_Exterior_08_20_08.jpg



Photo 7 - 350100_Cabinet_Interior_Front_08_20_08.jpg



Photo 8 - 350100_Cabinet_Interior_Back_08_20_08.jpg



Photo 9 - 350100_Leading_WIM_Sensor_08_20_08.jpg



Photo 10 - 350100_Trailing_WIM_Sensor_08_20_08.jpg



Photo 11 - 350100_Leading_Loop_08_20_08.jpg



Photo 12 - 350100_Trailing_Loop_08_20_08.jpg

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/200</u>	<u>08</u>

1.	DA	ATA PROCESSING –
	a.	Down load – State only LTPP read only LTPP download LTPP download and copy to state
	b.	Data Review – State per LTPP guidelines State – Weekly Twice a Month Monthly Quarterly LTPP
	c.	Data submission – State – Weekly Twice a month Monthly Quarterly LTPP
2.	ΕÇ	QUIPMENT –
		Purchase – State LTPP
	b.	Installation − ☐ Included with purchase ☐ Separate contract by State ☐ State personnel ☐ LTPP contract
	c.	Maintenance – Contract with purchase – Expiration Date _5 years from installation _ Separate contract LTPP – Expiration Date Separate contract State – Expiration Date State personnel
	d.	Calibration – Vendor State LTPP
	e.	Manuals and software control − ☐ State ☐ LTPP
	f.	Power – i. Type – Overhead Underground Solar ii. Payment – State LTPP N/A

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/200</u>	<u>08</u>

	g.	Communication –
		i. Type – ii. Payment –
		☐ Landline ☐ State ☐ LTPP
		Other N/A
3	DΛ	AVEMENT –
٥.	a.	m.
		Portland Concrete Cement Asphalt Concrete
	b.	Allowable rehabilitation activities –
		Always new
		Replacement as needed Grinding and maintenance as needed
		Maintenance only
		No remediation
	c.	Profiling Site Markings –
		Permanent
4.	ON	N SITE ACTIVITIES –
	a.	WIM Validation Check - advance notice required $\underline{2}$
	b.	Notice for straightedge and grinding check - $\underline{2}$ days \boxtimes weeks
		i. On site lead – State
		☐ State ☐ LTPP
		ii. Accept grinding –
		State
		□ LTPP
	c.	Authorization to calibrate site –
		State only
	d.	Calibration Routine –
		 ✓ LTPP – ☐ Semi-annually ✓ Annually ☐ State per LTPP protocol – ☐ Semi-annually ☐ Annually ☐ State other –

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/2008</u>	3

	e.	Test V	Vehicles Trucks –			
		1.	1st – <u>Air suspension 3S2</u>	State	⊠ LTPP	
			2nd – <u>3S2 different weigh</u>		State	\boxtimes LTPP
			3rd –	State	LTPP	
			4th –	State	LTPP	
		ii.	Loads –	State	\boxtimes LTPP	
		iii.	Drivers –	State State	\boxtimes LTPP	
	f.	Contra	actor(s) with prior successful exp	erience in WIM	I calibration in	state:
	g.	Acces	ss to cabinet			
		i.	Personnel Access –			
			☐ State only			
			⊠ Joint □ LTPP			
		::	_			
		ii.	Physical Access – Key			
			Combination			
	h.	State 1	personnel required on site –	☐Yes ⊠No)	
	i.	Traffi	c Control Required –	☐Yes ⊠No)	
	j.	Enfor	cement Coordination Required –	☐Yes ⊠No)	
5.	SI		ECIFIC CONDITIONS –			
	a.	Funds	and accountability –			
	b.	Repor	rts			
	c.	Other				
	d.	Specia	al Conditions –			
6.	CC	ONTAC	CTS –			
	a.	Equip	ment (operational status, access,	etc.) –		
			Name: Roy Czinku	Phor	ne: <u>(306) 653-6</u> 6	<u>627</u>
			Agency: <u>IRD</u>			

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/200</u>	8

b.	Maintenance (equipment) –	
	Name: Roy Czinku	Phone: (306) 653-6627
	Agency: <u>IRD</u>	
c.	Data Processing and Pre-Visit Data -	-
	Name: Roy Czinku	Phone: (306) 653-6627
	Agency: <u>IRD</u>	
d.	Construction schedule and verification	on —
	Name:	Phone:
	Agency:	
e.	Test Vehicles (trucks, loads, drivers)	_
	Name: Scott Sunderland	Phone: <u>(602)</u> 463-8007
	Agency: Otto Logistics	
f.	Traffic Control –	
	Name:	Phone:
	Agency:	
g.	Enforcement Coordination –	
	Name:	Phone:
	Agency:	
h.	Nearest Static Scale	
	Name: <u>TA Travel</u> Lo	ocation: Las Cruces, NW Exit 139
	Phone:	

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[35]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

1. * D	ATE OF CALIBRATION (MONTH/DAY/YEAR) [8/2	20/2008]
2. * T	YPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIER X_ BOTH
- <u>-</u> -	EASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION OTHER (SPECIFY)LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
 	ENSORS INSTALLED IN LTPP LANE AT THIS SITE (C _ BARE ROUND PIEZO CERAMIC BARE F _ CHANNELIZED ROUND PIEZO LOAD C _ CHANNELIZED FLAT PIEZO X INDUC _ OTHER (SPECIFY)	HECK ALL THAT APPLY): FLAT PIEZO BENDING PLATES CELLS _X_ QUARTZ PIEZO TANCE LOOPS CAPACITANCE PADS
5. EQ	UIPMENT MANUFACTURER IRD/ PAT Traffic	
	WIM SYSTEM CALIBRA	TION SPECIFICS**
6.**CA	LIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N	N) <u>X</u> TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED A MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW 5.0 DYNAMIC AND STATIC SINGLE AXLES 2.1 DYNAMIC AND STATIC DOUBLE AXLES 5.7	STANDARD DEVIATION1.6 STANDARD DEVIATION2.3
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATE	ON WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	55 70 75
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW	V SPEED) <u>3332/2975</u>
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) IF YES, LIST AND DEFINE AUTO-CALIBRAT	
	CLASSIFIER TEST S	SPECIFICS***
12.***	METHOD FOR COLLECTING INDEPENDENT VOLUMENT VIDEO X MANUAL	ME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIME X NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 0 FHW	VA CLASS <u> </u>
	*** PERCENT "UNCLASSIFIED" VEHICLES: 0.0	VA CLASS
	ON LEADING CALIBRATION EFFORT: <u>Dean J. Wolf,</u> 'ACT INFORMATION: <u>301-210-5105</u>	MACTEC rev. November 9, 199

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[35]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

1. * D	ATE OF CALIBRATION (MONTH/DAY/YEAR) [8/21	/2008]
2. * T	YPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIER _X_ BOTH
- <u>-</u> -	EASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION OTHER (SPECIFY) <u>LTPP Validation</u>	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
 	ENSORS INSTALLED IN LTPP LANE AT THIS SITE (CH_BARE ROUND PIEZO CERAMICBARE FL_CHANNELIZED ROUND PIEZOLOAD CHANNELIZED FLAT PIEZOX INDUCT_OTHER (SPECIFY)	ECK ALL THAT APPLY): AT PIEZO BENDING PLATES ELLS QUARTZ PIEZO ANCE LOOPS CAPACITANCE PADS
5. EQ	UIPMENT MANUFACTURER IRD/ PAT Traffic	
	WIM SYSTEM CALIBRAT	ION SPECIFICS**
6.**CA	LIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N)	X TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	PASSES PER TRUCK TRUCK TYPE SUSPENSION 1
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW	STANDARD DEVIATION2.4 STANDARD DEVIATION2.7
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATIO	N WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)65	
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW	SPEED)3146/2809
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) IF YES, LIST AND DEFINE AUTO-CALIBRATION	
	CLASSIFIER TEST SE	PECIFICS***
12.***	METHOD FOR COLLECTING INDEPENDENT VOLUME VIDEO X MANUAL	E MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIME _X NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 0 FHWA	A CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES: <u>0.0</u>	A CLASS
	ON LEADING CALIBRATION EFFORT: <u>Dean J. Wolf, N</u> CACT INFORMATION: <u>301-210-5105</u>	ACTEC rev. November 9, 19



Traffic Data N TEST TRUCK # 1 2.* Number of Axl s lbs / kg ab Over Engine Convent b) * Model:	les 5 tional b) * S	-	9 1 0 09 Jz:
2.* Number of Axl s lbs / kg ab Over Engine Convent b) * Model:	tional b) * S	Sleeper Cab? 🏽 🏈 N	
ab Over Engine Convent b) * Model:	tional b) * S	Sleeper Cab? 🏽 🏈 N	ys
ab Over Engine Convent b) * Model:	tional b) * S	Sleeper Cab? 🏽 🏈 N	ys <u>2</u>
ab Over Engine Convent b) * Model: 1400; on Description:	oxded even ly	-	
b) * Model:9400; on Description: cs of fine bullings 1	oxded even ly	-	
b) * Model:9400; on Description: cs of fine bullings 1	oxded even ly	-	
on Description:	orded evenly	dong thiler	
es of fine bullings)		dong thiles	
		Honey Asiler	
units):			
units):			
units):			
units):			
m / feet and inches / (eet and tenths		
B to C	C to D	33.2	
D to E 4.1	E to F		
d A to last)	Computed	59.1	
xle B (units) + \	.8')	
(+ i	is to the rear)		
15.* Suspension Descrip	tion (leaf, air, no.	of leaves, taper or flat lea	ıf, etc.)
2 full had spring			
. *			***************************************
<u>>\(\cdot\) \(\cdot\) \(\cdot\)</u>			THE RESERVE OF THE PARTY OF THE
Sie			
<u> </u>			
	m / feet and inches / (B to C	D to E 4.1 E to F d A to last) Computed xle B (units) (+ is to the rear) 15.* Suspension Description (leaf, air, no 2 foll last Spring 3.6 3.6 3.6	m / feet and inches / feet and tenths B to C

Sheet 19	* STATE_CODE	3 5
LTPP Traffic Data	* SPS PROJECT ID	0 1 0 0
*CALIBRATION TEST TRUCK #_1_	* DATE	00120106

PART II

Day 1

*b) Average Pre-Test Loaded weight

76820

*c) Post Test Loaded Weight

7/0030

*d) Difference Post Test – Pre-test

-790

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	Mayo	16480	16480	6110	16110		76820
2	11620	16430	16480	10150	16120		76820
3							
Average	11630	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	16480	(4)15	1615		76820

Table 6. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average						**************************************	

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11340	10350	16350	16040	16040		7666
2	11340	16320	16320	theolo	16010		76000
3							
Average	11340	16320	16320	16025	16025		76030

Measured By	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	Verified By	Weight date	
	Y Y/			1

		Sheet 19		* S	TATE_CODE		3 5
		TPP Traffic Data			PS PROJECT II)	0 1 0
L Rev. 08/31/0		TION TEST TR	UCK # 1		PATE		9/2/2
				Day 2			
7.2		e Pre-Test Lo		77066)		
	•	st Loaded We	***	16280			
	"d) Differe	nce Post Test	– Pre-test	181	<u> </u>		
able 5.2.	Raw data – A	xle scales – pr	e-test				
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
<u></u>	11800	16550	16550	14090	16090		77080
	1740	16550	16550	16090	16090		77040
verage	11780	16550	16550	16020	160°10		77060
Sable 6.2	Raw data – Az	vle scales					
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
verage							
	Raw data – Ax						
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
	11420	1/3/0	16360	16020	16070		76280
	10000	16360	16360	16060	16060		76280
	- introduced to the second	A AMADON SAN SAN SAN SAN SAN SAN SAN SAN SAN SA	meron martinessamona (commente environdo de commente en commente en commente en commente en commente en commen				
verage	11430	16360	16760	16065	16065		76290

Weight date \$\lambda_1\lambda_2\lambda_

_____ Verified By _____

Measured By ___

Sheet 19	* STATE_CODE	3.5
*CALIBRATION TEST TRUCK # 2	* SPS PROJECT ID	0 1 0
Rev. 08/31/01	* DATE	0812010
PART I.		
1.* FHWA Class 2.* Number of Axles	s Number of weig	ght days
AXLES - units - (bs/ 100s lbs / kg		
GEOMETRY		
8 a) * Tractor Cab Style - Cab Over Engine Convention	onal b) * Sleeper Cab? $\mathring{\mathcal{D}}$ /	N
9. a) * Make: () * Model: w/		
10.* Trailer Load Distribution Description:		
pulletized super sacks of time buffings	loaded evenly along teiler	
	~	•••
		ne.
11. a) Tractor Tare Weight (units):		
b). Trailer Tare Weight (units):		
12.* Axle Spacing – units m / feet and inches / feet	et and tenths	
A to B <u>20.0</u> B to C <u>4.3</u>		
D to E	E to F	
Wheelbase (measured A to last)	Computed 61.1	
13. *Kingpin Offset From Axle B (units) + 1.3	to the rear)	
	· · · · · · · · · · · · · · · · · · ·	
SUSPENSION		
Axle 14. Tire Size 15.* Suspension Description	on (leaf, air, no. of leaves, taper or f	lat leaf, etc.)
A 750245 2 full lest spring	\	
C <u>15024.5</u> <u>Sc</u>		
D <u>wa 22.5</u> <u>Sic</u>		
E 11/22.5		
F		······································
6420060018_SPSWIM_TO_16_35_2.81_0100_Sheet_19_axle_sc	cales_truck_2.doc	

Sheet 19		* STATE_CODE	_3_5_
LTPP Traffic Data		* SPS PROJECT ID	0 1 0 0
*CALIBRATION TEST TRUCK #_2		* DATE	8/20/06
7. 08/31/01			•
RT II			
· · · · · · · · · · · · · · · · · · ·	Day 1		

Table 5. Raw data – Axle scales – pre-test

*b) Average Pre-Test Loaded weight	67200
*c) Post Test Loaded Weight	66570
*d) Difference Post Test – Pre-test	- 630

Axle A Axle B Axle C Axle D Pass Axle E GVW Axle F 15870 15370 00563 12000 11730 11730 1 12040 15820 67200 2 15620 11760 W760 3 15845 11745 158 45 11745 12020 67200 Average

Table 6. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average				A STATE OF THE STA		Operand in some family on pulsary and the second an	

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11640	15730	15730	11640	11640		66380
2	(1660	15750	15750	11600	N 6.00		46360
3							
Average	11620	15740	15740	11620	Word	THE REPORT OF THE PARTY OF THE	66370

	% ~.			н с
Measured By	**************************************	Verified By _	Weight date	\$ \[\frac{1}{20} \left\ \frac{\partial 0}{20} \]

		Sheet 19			TATE CODE		3 :
	······································	TPP Traffic Data		······································	<u>PS PROJECT II</u>)	0.1 (
L Rev. 08/31/0		TION TEST TRU	CK # 2		ATE		<u> </u>
ICCV. 00/31/0	.1						
				Day 2			
7.2	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	e Pre-Test Load	***	67330	NOTIFICATION OF BEAMARIES AND		
	· ·	st Loaded Weig	w-	<u> </u>			
	*d) Differer	nce Post Test –	Pre-test		<u> </u>		
Table 5.2.	Raw data – Az	kle scales – pre	-test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
	12040	15940	15940	טורט	117710		67340
2	12120	15%80	15ଅଟ <i>ା</i>	11720	U72⊅		67320
3							
Average	12080	15910	15910	11715	11715		67330
Гable 6.2.	Raw data – Ax	kle scales –					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1 .							

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1 .							
2		7.0					
3							
Average	And the second s			**************************************			

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11760	15740	15740	11630	11630		W500
2	1080	15730	15730	11630	11630		66500
3							
Average	Maria	15735	15735	11630	11630	WOOD IN HIMMOOD AND A STORE AS A	66500

Measured By \(\lambda\)	Verified By	Weight date	8/21/03
-------------------------	-------------	-------------	---------

Sheet 20	* STATE_CODE	3 5
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
Speed and Classification Checks * \ of* \	* DATE	8/25/08
Rev. 08/31/2001		

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
68	9	33659	68	9	65	5	33811	63	General Control of the Control of th
72-	9	33754	73	9	60	Andrew Control of the	33812-	60	lance of the same
25	9	33708		9	69	2	33815	67	9
C 3	9	33711	<u> </u>	9	7/	6	33819	4 71	- G
80	9	33728	80	9	74		3372)	74	American American American
66	9	33736	67	Ø	75	2	39827	74	9
72	9	33744	72	g	75		338 m	25	9
67	2	33747	67	g	Ġ\$	9	3384F	من من	9
75	15	3375	many perfection	in second	67	9	33 8 52	67	9
79	9	33) 5 3	79	9	52	6	3385Y	52	6
85	9	33754	83	g p y y	75	9	33863	フ サ	9
73	9	33756	73	9	66	9	33862	Contraction of the Contraction o	9
62-	9	33757	62	2	Lange Lange		3387/	was to be a few of the same	Comp.
<i>C</i> 2.	11	33747	63		76	S	3 3323	フキ	9
65	9	33768	66	2	72.	9	33875	71	9
7.5	9	23773	-72	9	9	.O	33877	70	9
ラフ	9	33776	フム	- 9	()	9	33886	45	g
69	9	33786	63	<i>5</i> 3	C.S.	9	33889	68	
63	8	33782	65	Ø	<u> </u>	9	33894	(a)	9
67	9	33791	66	9	7/		33.90 9	Constitute	9
72	5	33093	<u> </u>	5	68	6	33911	68	6
65	9	33799	66	9	72		33912	72	, S
G4	9	33840	63	9	66		3 <i>3917</i>	66	S.
70	J	33753	2/	S	72	2	33923	7/	g
68	9	338° 6	66	9	74	Land Company	33927	73	9

Recorded by MAPL 2 Direction \(\sum_{\text{Lane}} \sum_{\text{Ime}} \) from \(\frac{955^{\text{Arr}}}{2} \) to \(\frac{11 \cdot 21 \text{P}^{\text{M}}}{2} \) 6420060018_SPSWIM_TO_16_35_2.81_0100_Pre-Validation_Sheet_20.doc

Sheet 20	* STATE_CODE	3_5
LTPP Traffic Data	*SPS PROJECT_ID	0_1_0_0_
Speed and Classification Checks * 2 of* 2	* DATE g / 2=	/ 68

Rev. 08/31/2001

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class
66	5-15g	33923	65	5	75	9	34533	73	9
72	9	33942	73	9	68	CO	34038	6)	9
<u>69</u>	9	33950	68	9	(Jan	C)	34544	62	9
70	9	33952	(4)	9	70	9	34049	70	9
67	9	33258	65	Ŷ	68	9	34054	66	Si
70	Sign Control of the C	33 <i>9</i> 6.1	49		65	- Care	34060	CH	9
45	9	33965	63	9	"7/		34~62	69	6
63	9	33968	67	9	73	9	34068	72.	G
67	9	3377	67	<i></i>	69		34370	67	<i>g</i> 11
678	9	23978	lo la	G.	C 54	1 Danier	3457)	64	12
72	9	33,980	7/		63	9	3472	<i>(</i> 3	9
	Ğ	33982	74	6	75	July 1	34077	anna Jan	5
79	Bitter.	33985		\$5	4 ()	3	34082	66	9
64	9	33486	64		68	9	34086	68	9
68	9	3 3988	Ç (٧	60	.5	34090	67	5
gers Breeze	9	33289	64		64	9	34901	Go James	
69	Cay	33995	67	9	70	9	34254	6.5	9
73	9	33995	70	9	65	9	34095	·63	9
62	8	34002	63	B	72		34101	Joseph	9
77	9	24°5	77	9	Samuel Comment	_J	34111	In Color	9
) 5	e de la constante de la consta	34015	76	9	65	S. Carrier	35/14	7865	. Janet
	9	34946	72	÷7	68	9	35115	66	9
74	9	340238	524	2	67	9	34118		<i>g</i>
72	3	34-24	71	Ĵ.	71	5	34120	63	9
75	g	3402)	<u> </u>		75	9	34125	75	ġ`

Recorded by __MATZ_K ____ Direction ___ Lane ___ Time from __//21 _PM to /_2123 PM 6420060018_SPSWIM_TO_16_35_2.81_0100_Pre-Validation_Sheet_20.doc

Sheet 20	* STATE_CODE	_3_5
LTPP Traffic Data	*SPS PROJECT ID	0 1 0 0
Speed and Classification Checks * / of* 2	* DATE	08/2/108

Rev. 08/31/2001

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
70	9	34293	70	S 9	75	9	36440	68	9
70	Ś	36304	69	8	65	9	36472	64	9
71	C)	363 0 5	<i>6</i> 871	.9	66	9	36444	66	9
7	J	36311	75	9	68	9	36454		5
60	9	36313	5.9	9	67	9	3(455	66	9
63	2	36329	62	9	74	5	36456	75	5
63.	9	36346	63	9	フサ	6	34458	6 74	66
66	9	3635)	blo	9		9	36460	66	9
73	9	36361	and the second	9	73	9	36462	72	9
61	<u> </u>	36368	<i>5</i> 8	9	68	9	36463	69	C)
67	Ş	36369	65	9	65	9	36469	65	9
71	9	36377	71		65	8	36488	64	8
73	9	36378	73	9	62	9	34483	60	9
82	.53	34381	60	9	68	25	36484	68	9
66	8	36385	<u>(5</u>	Ê	73	9	36488	72	89 9
GT 62	64	36 8 9 3	<i>6</i> 3	4	73	9	36485	72	50
67	9	36354	()	9	68	9	3492	66	9
60	9	36395	ÇO	9	7)	<i>9</i>	36494	70	9
67	8	36400	(a)	િ	80	9	36542	79	9
65	9	36419	65	9	(S	9	36516	C. E.	9
>> >	8	36424	H	É	6	9	36521	61	9
<i>-</i> 22,	9	36422	6	9	48	5	36522	67	5
80	2	36425	79	9	65	9	36536	64	Large B
73	9	3 GH30	<i>7</i> 4	9	65	9	36534	65	9°
73	Î	36437	72	2	74	Parameter In section	36544	£72	5
Recorded	by AAA	[2K_3	Dire	ction 👠	Lane _	<u> Time</u>	from <u>9:45</u>	<i>}}</i> ^∿to <u></u> /□	:42 AM



Sheet 20	* STATE_CODE	3_5
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
Speed and Classification Checks * \nearrow of* \nearrow	* DATE	08/21/08
Post 08/21/2001		

Rev. 08/31/2001

W)	IM eed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
5	٥	8	36955	70	8	67	9	34658	65	9
Co	O	9	36558	59	CZ)	70	6	36668	6.9	6
6	5	5	3 65 59	62	5	47	Col	36670	66	C)
4	B	11	36560	63	11	<i>45</i>	12	36671	65	12
6	2	9	36572	67	9	67	8	34673	67	8
6	4	6	36578	GE)	E	68	8	36674	67	8
6	, series Secretarion	9	34583	61	9	67	6	36028	66	6
60	Z	E	34525	63	5	71	8	34495	70	8
as	 >	9	36586	64	9	73	9	36686	73	9
6	7	9	365m	66	Š	67	gener Ger	36688	67	lance.
50	6	9	3653	57	9	66	5	Z669 9	68	leave.
G.C	P	9	36603	66	9`	75	9	36694	Xiiii	9
7	Ö	9	36604	80	9	74	- Company	36695	72	5
75		9	36615	74	9	56	5	36783	57	Processor.
7.	3		36612	72.	J	68	9	36704	68	9
7	3	9	3663	25	9		9	36795	74	9
67	7	9	36614	7)	S	77	Sec. 12	36746	77	w. G
フた	>		36616	69	S. S	68	9	36757	68	9
ζ:	9	9	36618	74.60	9	64	.9	36710	3	
G:	9	9	36635	6.3	<u>G</u>	68	9	36717	67	9
6.	Alien .	9	36631	6.0	Ş	75	2	36719	75	S
6.	2	9	36633	68	-5	76	9	36723	76	9
6.		9	36634	64	9	78	9	36726	7)	- G
77)	e.***;	34656	79	C.	69	9	2(72)	68	9
	5	9	36657	64	3	76	9	30730	75	<u></u>



* STATE CODE 3 5	*SPS PROJECT ID 0 1 0 0	* DATE 8 / 20 / 25
 Sheet 21	LTPP Traffic Data	WIM System Test Truck Records of 3

E-F space																
D-E space	and a second	04	1/Barriage con	9	- July	9	÷	0	1000 (1000) 1000 (1000) 1000 (1000) 1000 (1000) 1000 (1000)	3	J.	<i>Ş</i>	Jungan Serias di Aurolan	0		3
C-D space	22	o de	8	07 CA	32.4	8	83.8	か が で	(10) (10)	S	7	W	8.8	0.55	(N)	53
B-C space	3	J.		C C	3	3	<i>3</i> -	J MAN	T T	3		j	- June	*	73	M
A-B space		0,	Š		52	Á		Å	1	n NS	J. S. S. Stronger	6 5	N.	Å	V	4
@\\M	8 27	8.02	Z	783	S.	The second	7	A STATE	79.74	4	\$ 28	8.69	& & &	0 %	QE.	000 17
Axle F weight																
Axte E weight.	9263	4768	164	gh	98H5	Z	47.00	2	39/25	0	(8)	200 Cas	18 July 18 Jul		62/76	96
Axle D weight.	10/20	B	99/6	17.5%	5726	W So	976	3	98/8 186	Q. E.	272	THE STATE OF THE S	100	B. B	23/20	25/2
Axle C weight.		TEL	29/7B				837 R	23	781	80 100 100 100 100 100 100 100 100 100 1	£ 33		24 S			(F) 10
Axle B weight.	25	Chec	957 176	72/20		79/92	J CS	200	100	Ž,	28/758	76	798	78/2	100	200
Axle A weight.	02/56	36	78	5913	20	100	45/cg	1785	45/29	E9/65	75/25		75/69		25/29	7/35
Speed	0	5	8	()	S	R	(5)	ÒE.	0		Eg	89	0		2	76
Record No.	# 60	32478	3226		Ž.	33,556	84.7EE	361	23307	33713	33004	322	3383	33831	W E	22.828
Time		%	Ş	yn Go		S	9:32	50 50 50 50	200	20 20	S.	<u>S</u>	(C.O)	85:0	25.6	03 V3 (e)
Pass		Maria mayon	~~{	6	4	(r)	and the second	Ť	l.s	W	\ <u>\</u>		7		0 00	(50)
Truck	"("man fiyelus bus	Cb	€>>1.802 b (5.6-p.	<6	II Alususas _{ia}	Ç	Soldistreme	C-f	America	cl	entines sin	d	Manahari (a) Prin	d	estimentary.	C.P
Radar Speed	Ca	2	10 00	2	67		0	29	(5)	10		9	67	2	g G	2.
Pvmt	127	12 0	2	19		00	W	G	, 00 5, N	in E	is a	(S)	n	<u>2</u> N	<u>S</u>	Se Se

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Shoot 21	1 * CT A TD COND	14 C
SALVOL & A	SIAIL CODE	J. C.
Data	*SPS PROJECT ID	0 1 0 0
WIM System Test Truck Records 2. of 3	* DATE	WO - 05 - 8

E-F space																
D-E space	, Lander	0 5	gamaina L	2	eronament,	3	-F	9	epotentian Marian	3	The second	9.	Contraction of the second	3	and the transporting and and a significant and a significant and a significant	3
C-D space	2.25	8	3	e K	6.0 6.0	a di	CO CO	7 K	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	0.00	73.0	(A) (A)	E NO	m m	C S S	Ŕ
B-C space	3	ナチ	7	き	3	and a	n E	J	ister S	indigen.	t	3	<i>t</i>	Ĵ	Ť	3
A-B space	ls.	o L	L)	9		000	270	\$	70	2	10	8	V.	d E		<u>a,</u>
@W	<u> </u>	0 de 1	8	(8		3	Sum.	6,3	200	R R	2	6.33	Z	00 6 9	Ŕ	726
Axle F weight																
Axle E weight.		7% 8	Z	99/2	20°	22		82 N		Z Z	28/2	100	Ž Ž		100	9:10
Axle D weight.	N SE		£15	12/15	25		186		200		25	M.	25	JA.	# A	N
Axle C weight.	200	20/2	2/23	70	Take To the Control of the Control o	TO STATE OF THE ST	928	3/2	78/81	J. O.	7%s	Salar Salar		16	\$. \$2	262
Axle B weight.	37/2	26/20	M	18	16/5B	MOZ	86/23	N. C.	26/38			7 John	357	700	28/23	RAGE OF THE SECTION O
Axle A weight.	500	0764	75	5863		1965	50%	8	7.5%	S CO	Ž O	5/61	SH S	57/13	2565	3
WIM Speed	79	68	Š			8	9	10	Co	60	C.S.	(J	62	165	20	0
Record No.	32947	33945	245	N. S.	34118	P T	× ×	To the		2 3 5 5 5	30.5	13:26 3438	37	15818	34924	P S
Time	9	8	gairean Area ang e cannag	\$	2.13	222			8	3.5	3	220	33	3	14:0H	J.
Pass	<i>```</i>	67		Ç.	generalis	_{pr} ancisti. Lincolnin	frank.	()	(4)	(2)	£	-11-10-10-11 -11-10-10-11	2	12	, mon	N.S.
720	- and the same of	· <\	mla ben (gira) jago,	d	**************************************	6	e (sept) statement	d	Allongopalites	Z	(months to the first	d	· white sections .	d	A Frankasynag	. 4
Radar Speed	C	(S)	Œ	R	S	V		Ž	63		maran.	iv.	(2)	7	S	2
tem p	111	74	ST N	S. C.	Ž	X	Ŋ	Ü	20 20 70	13. N	57.2	Ų V	S	01 0	(5)	CA CA Carrent

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3.5	D 0 1 0 0	8/20/08
* STATE CODE	*SPS PROJECT	* DATE
Sheet 21	LTPP Traffic Data	WIM System Test Truck Records 🔰 of 💪

E-F space													
D-E space		<i>0</i>	Michael Market M	9	3	÷	3	3					
C-D space	100 m	00	W	Có Có	800	22.2	Š	S	·				
B-C space	3	M)	Ŧ	j	Ĵ	4	arjer Jan	(n)					
A-B space	N C	©	N C	Á	- Janes	<u>5</u>	IN C	3					
@WW	60 60	3) R	K	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	0 35	70,3					
Axle F weight			***************************************										
Axle E weight.	\$ 60 mg	3	54 free 54/26	53/2 2/5	200	C. C.		7					
Axle D weight.	R	9 J	E E	200		13	10 CC	E.					
Axle C weight.	1987		<u> </u>	76/2	200	1	Z8/82	9					
Axle B weight.	851 195	13/22	Z.			20	200	200					
Axle A weight.	6752	23) M	94°6	G.C.	77	70	25 June 17	23					
WIM Speed	(9		T	0	0	inemar.	Carl	59					
Record No.		S A S		2002 P. A.	60	3854,8	34648	395					
Time	57:5/	R	Z Ž	any can		24	10 2 S	Ų Š					
Pass	enessess.		Section .	<u>0</u>	Ë	Ō	30	Q.	-				
Truck	genille (Silitation	C.S	,mgm\\\/\	d	The state of the s	CE	w//esspec	сb					
Radar Speed	29	S	2	70	G	~~~		3					
Pvmt temp	<u>u</u>	J	10 2 2		<u>0</u>	10 2 2	2	<i>\$</i> 2					

15.C

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Sheet 21	* STATE_CODE	3.5
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
WIM System Test Truck Records of	* DATE	8/21/2003

E-F space															
D-E space	3	- Andrews	2		3	The state of the s	orezonya a dipor	Albanian .	3:		2				
C-D space	er.	(A)	2000	3	E S	100 100 6.23	(2)	33.5	(4)	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	e di				
B-C space	7	infor augus	3	Ŧ	ý Ý	migun.	and the	3	žů. (k)	7	in farm				
A-B space	9	3	a A	Same of the same o	e.	C.	Á	in C	0.63	2.5	0 3				
@.	(#)) "C	10	ナド	6	6.77	00	Sign		13,	6.9				
Axle F weight															
Axfe E weight.	25		2%	20	Z.	K K	R R	R. A. C.	Z Z		jû B				
Axie D weight,	95	(J	Ž,	7	CE NO	30	100 200 200 200 200 200 200 200 200 200	Z Z	E E	36	35				
Axie C weight.	(%)	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	~ BJ				188	20	Ž	\$ 8 \$ 8	2000				
Axle B weight.	5	X	13 1 1 8 Sec.	78	8	20	1000	8	200	100	J. R.				
Axte A weight.	<u>v</u>	33		22/23		25.00		100	72						
Speed		Š	26	G	0	G	6	0		c.l	R			***************************************	
Kecord No.		36.86	83	3.2K	2)+7.7E	36356	732D	69598	362	2000	124.7%				
		82	8.28	\$5.5		4	A	3	3	700	24787551				
Tass S	particularies.	angent files	C		(0)	W	- and	*			Ġ	É			
× S	les.	omersially.	d	g _{//k} assarr	d	toctokaja-	d	A Grand Anna de la constante d	d	⁴ No state of the state of th	~6	alke	eak.		
Speed	20	00		65	3	6		300	7	CS	N.			······	
temp (is desired	G)	M ∞	() (%	5	in N	200	1.0	ri Š	20	0)				

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Sheet 21	* STATE_CODE	3.5
LTPP Traffic Data	*SPS PROJECT ID	0 1 0 0
WIM System Test Truck Records of 2	* DATE	100 - N

E-F space																	
D-E space	constitution of the	0 5	- Marine Services	O.	gramman agent in manageness manageness	? 	and the same of th	9	constanting	3	- American	Q.	- Section - Sect	9	and and a second a		
C-D space	33.3	3	33	(A)	j K	8	8 8	2	33.53	N N N N N N N N N N N N N N N N N N N	3	33.0	S. S.	22	S.	1	
B-C space		3	J.	J Z	1	South South	3	Ť)	Ť	3	enga.	Ť	3	J	4	
A-B space	5	games (Ŝ	N	Ŕ	K	Ĝ	D	d A	10	0.3	5	Ä	LA C	id S	
GVW		200	600 2000	43	23.65	07.00	800		200	- ôg	& 0,	3	7.6		7 \$\sqrt{\pi}\$	933	
Axle F weight								,									
Axle E weight.			70	Pa	25	M	8	1962	R Second	100 St.			ELJEB				
Axle D weight.	98 t	TO.	are, O a A annual B	1000	120	W.		7)/sz	E.	23	THE CONTRACTOR	S. C.	746	75/5	No.	N N	7774
Axle C weight.	88		95	63/70	200	E	700		182 1	13.50 P		88/50	79/83	18/2	38/62		ļ
Axle B weight.	25	76	785	68/ac	182		S	79/04			JO.	TAL	8	18	26/28	No.	3000
Axle A weight.	Se S		25/29	1965	19/25	77/25	6/56	S. C.	85%		The state of the s	77/25	Ja Ja	62/3	35/5	M	3
WilM Speed	Q	56	69	97	(9	K	(J.	10	3	50	60	75	G	65	6. Om	No.	
Record No.	3652	3624	325	3664	CD 75	3 995	3000	3716	303	31.9E	36361	3696	350	3008	R R	R	
Літе	[5:23	おら	5	¥ 2	92.	96	C	11:28	11-43	8	65:71	12:58	13:18		2.60	13:2	
Pass	2			Ø	60	Ø)	87	. sum	0	enember Stranger	energen ja	4	San		B	YAY	·
Truck	WITCHALL COMPAN.	d	Aprillation	ch	Al Inggolycig.	cb	* ***mare	À	с-үүдэхгэчи?	N	Prodesta (1866)	Ŋ	al-inequiplation .	CP	yyandyddiridda	75	
Radar Speed	23	Ŋ	5	Š	Ŋ		7	S S	S	È		L M	19	t	"ormore"	ÿ	
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Sheet 21	* STATE CODE	3.5
LTPP Traffic Data	*SPS PROJECT_ID	0 1 0 0
tem Test Truck R	* DATE	8/21/88

E-F space																
D-E space	5	The state of the s	and and a	-	- A	in t	<i>9</i>	sseemer Jun	0	9	g A	annan, Marin	.avan	.assessment	9	
C-D space	830	iv iv	27.0	3.2.2	22.22	t R	8	la la la	387	, in the second	8	33.3	33.2	33,3	23.2	
B-C space	ned ned ned	3	F F	J.		Ĵ	N		Ì		og gr	5	t	+	Ť	
A-B space	o A	60	200		Ä	U,	O S		0,40	27.	007	5'4	3	ナニ	Á	
GVW	S	0.5.0	673	September 1	9:3	3.0	C.3	232	64.9	3.56	1.79	69.3	799	25.3	Š	
Axle F weight																
Axle E weight.	200			8	7	100	2	2000 S	723	4	21	34.5	27/28	7668	97/L	
Axle D weight.	The state of the s	9/16	Chy 189	N. S.	The state of the s	72		226	14		5. J. S.	92 J.	49/E	76/28	5	
Axle C weight.	A SO	20 J.	ES L	8		8			ZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZZ	77	6784	99/18	76/4	18/10	286	
Axle B weight.	Ž	C 1/23	127 200	700	2000	X	Porc	90	187	28 8 S	49/3	200	72/83	L8/86	18/12	
Axle A weight.	7 20	52/25	7	C363		N N	7763	200	27/2	17/85	S	St.	176	55/65	~%/s	,
WIM Speed	69	(3	B		89	89	09	6	76	19	\$	73	٥(ري (EL.	
Record No.	3225	\$100 70 h	14.52 312L		2012	14-44 3228	18254	3333	200	37997	2200	37452	54.65	6:12 37523	7724	
Тт	2.6	3	[4:5]			emakar emakar	y.	in S	3	sp Ci M	بر المال	15:50	i Si	7:3	4:2	
Pass	Signature States	A SECTION	rv.		9	7	(°	Carrier Carrent	() ()	Ø	<u> </u>	100	Q	20	C.	
Truck	CR	do moderns.	Ç	^{че} вімціож <i>ечн</i>	d	17°470(00)A		vonneg	d	**************************************	, c-}	completely.	C)	Marindon Managa	B	
Radar Speed	₹ 19	est es	63	Š	0	29	.3	S			83	62	67	67	動	
Fem p	£	C. C	S (T)		r.		N	Š	2		ż	6	200	82	8	

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Calibration Worksheet

Site: __350100___

Beginning factors:

Speed Point (mph)	Name	Left Sensor 1/3	Right Sensor 2 / 4
Overall			
Front Axle	dynamic lampensation	[86]	
Distance	distance (cm)	274	
1-(55)	88 100	3315	2962
2-(40)	96 kgs	3315	29162
3-(65)	105 Kph	3332	2975
4-(70)	102 kgh	> 533.	2975
5-(75)	120 4ph	5332	2975

Errors:

	Speed Point	Speed Point	Speed Point	Speed Point	Speed Point
	1 (55)	2(40)	3 (65)	4 (70)	5 (75)
F/A			* 2 . 1 4 2 .)	+2.5 +2.5	+1.5 +1.5
Tandem			+ \$ \$ +5.5	+ 4.0 +60	+ 5.7 45.7
GVW			+4,9+4,0	+ 5.3.45.3	+4.7 +4.7

Adjustments:

	Raise	Lower	Percentage
Overall	ACCHANGE OF THE PROPERTY OF TH		
Front Axle	M		3.42 %
Speed Point 1			
Speed Point 2			
Speed Point 3		N	5,23 %
Speed Point 4		X	5,57 %
Speed Point 5			5.07 %

End factors:

Speed Point (mph)	Name	Left Sensor 1/3	Right Sensor 2 / 4
Overall			
Front Axle	dynamic populasition	103	
Distance	distance (em)	576	
1-(55)	78 kph.	3315	2962
2-(60)	al Koh	3315	2962
3 - (65)	105 kph	315%	2819
4-(70)		314 6	2809
5-(75)	120 606	3163	2824

TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

August 20, 2008

STATE: New Mexico

SHRP ID: 350100

Photo 1 - 350100_Truck_1_Tractor_08_18_08.jpg	2
Photo 2 - 350100_Truck_1_Trailer_08_18_08.jpg	
Photo 3 - 350100_Truck_1_Suspension_1_08_18_08.jpg	
Photo 4 - 350100_Truck_1_Suspension_2_08_18_08.jpg	3
Photo 5 - 350100_Truck_1_Suspension_3_08_18_08.jpg	4
Photo 6 - 350100_Truck_2_Tractor_08_18_08.jpg	4
Photo 7 - 350100_Truck_2_Trailer_08_18_08.jpg	5
Photo 8 - 350100_Truck_2_Suspension_1_08_18_08.jpg	
Photo 9 - 350100_Truck_2_Suspension_2_08_18_08.jpg	
Photo 10 - 350100_Truck_2_Suspension_3_08_18_08.jpg	



 $Photo\ 1\ -\ 350100_Truck_1_Tractor_08_18_08.jpg$



Photo 2 - 350100_Truck_1_Trailer_08_18_08.jpg



Photo 3 - 350100_Truck_1_Suspension_1_08_18_08.jpg



Photo 4 - 350100_Truck_1_Suspension_2_08_18_08.jpg



 $Photo \ 5 - 350100_Truck_1_Suspension_3_08_18_08.jpg$



Photo 6 - 350100_Truck_2_Tractor_08_18_08.jpg



Photo 7 - 350100_Truck_2_Trailer_08_18_08.jpg



Photo 8 - 350100_Truck_2_Suspension_1_08_18_08.jpg



Photo 9 - 350100_Truck_2_Suspension_2_08_18_08.jpg



Photo 10 - 350100_Truck_2_Suspension_3_08_18_08.jpg

ETG LTPP CLASS SCHEME, MOD 3

Axle 1 Weight Min *						2.5				2.5	3.5	3,5			2.5	3.5	3.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross Weight Min-Max		0.10-3.00	1.00-7.99	1.00-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12,00-19,99	12.00 >	20.00 >	1.00-11.99	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20,00 >	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00>	20.00 >
Spacing 8																														3.00-45.00
Spacing 7																7,777				The second secon									3.00-45.00	3.00-45.00
Spacing 6	77718								312.00						***************************************													3.00-45.00	3.00-45.00	3.00-45.00
Spacing 5						700000000000000000000000000000000000000																				2.50-10.99	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 4																			1.00-11.99	1.00-11.99	2.50-6.30	2.50-11.99	12.00-27.00	2.50-6.30	11.00-26.00	2.50-11.99	6.00-24.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3			7,000,000										1.00-11.99	1.00-11.99	1.00-20.00	2.50-12.99	13.00-50.00	2.50-20.00	1.00-11.99	1.00-25.00	2.50-6.29	6.30-65.00	6.30-50.00	2.50-6.30	6.00-20.00	6.10-50.00	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 2							6.00-25.00	6.00-25.00	3.00-7.00	6.30-30,00	2.50-6.29	11.00-45.00	6.00-30.00	6.00-30.00	6.30-40.00	2.50-6.29	2.50-6.29	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 1		1.00-5.99	6,00-10,10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6.00-26.00	10.11-23.09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00
No. Axles		7	2	7	2	7	3	3	æ	33	e	3	4	4	4	4	4	4	ĸ	\$	S	w	\$	5	5	9	9	<u>r</u>	x	6
Vehicle Type	1	Motorcycle	Passenger Car	Other (Pickup/Van)	Bus	2D Single Unit	Car w/1 Axle Trailer	Other w/ I Axle Trailer	Bus	2D w/ 1 Axie Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 3SI	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/ 3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's
Class			7	60	4	S	7	6	4	'n	9	∞	7	3	S	-	%	×	3	w		6	6	6	=	10	12	13	13	13

Spacings in feet Weights in kips (Lbs/1000)
* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

New Mexico SPS-1 (Lane 1)

1st Validation

Calibration Factors for Sensor #1

Validation Visit	August 21, 2008	Installation Calibration	May 14, 2008
Front Axle	103	Front Axle	100
Distance	276	Distance	274
88 kph	3315	88 kph	3315
96 kph	3315	96 kph	3315
105 kph	3158	105 kph	3332
112 kph	3146	112 kph	3332
120 kph	3163	120 kph	3332

Calibration Factors for Sensor #2

Validation Visit	August 21, 2008	<u>Installation</u>	May 14, 2008
		<u>Calibration</u>	
Front Axle		Front Axle	
Distance		Distance	
88 kph	2962	88 kph	2962
96 kph	2962	96 kph	2962
105 kph	2819	105 kph	2975
112 kph	2809	112 kph	2975
120 kph	2824	120 kph	2975